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Associated Laboratory for Energy, Transports and Aeronautics



**ON THE LOSS OF ROLL CONTROL
INDUCED BY THE WAKE VORTEX HAZARD**

by

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at

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in

Lisbon University, Portugal

presented at

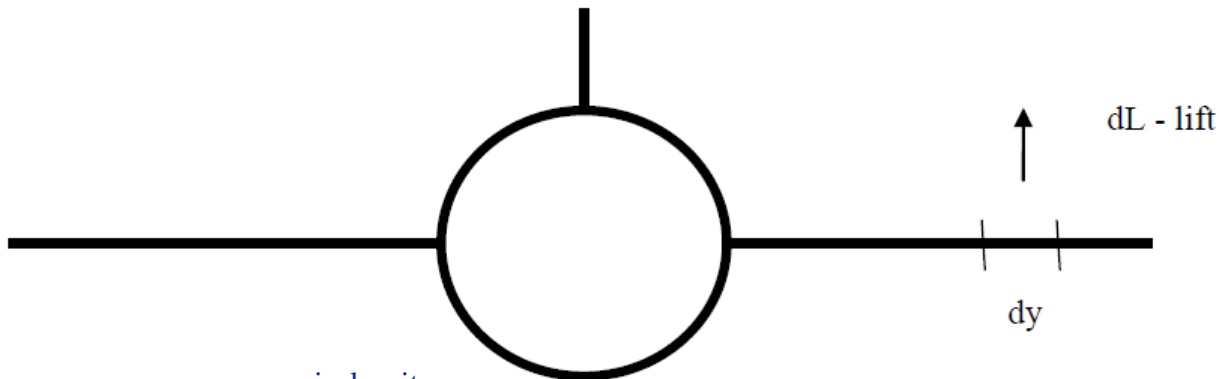
Wakenet-Europe Workshop 2014

on

13 May, Bretigny

Eurocontrol Experimental Center

Rolling Moment Induced on the Following Aircraft



$$dL(y) = \frac{1}{2} C_{L_\alpha} \rho U w(y) c(y) dy$$

lift slope \rightarrow C_{L_α} air density \rightarrow ρ airspeed velocity \rightarrow U downwash \rightarrow $w(y)$ wing chord \rightarrow $c(y)$ per unit span \rightarrow dy

$$R = - \int_{-b/2}^{b/2} y dL(y)$$

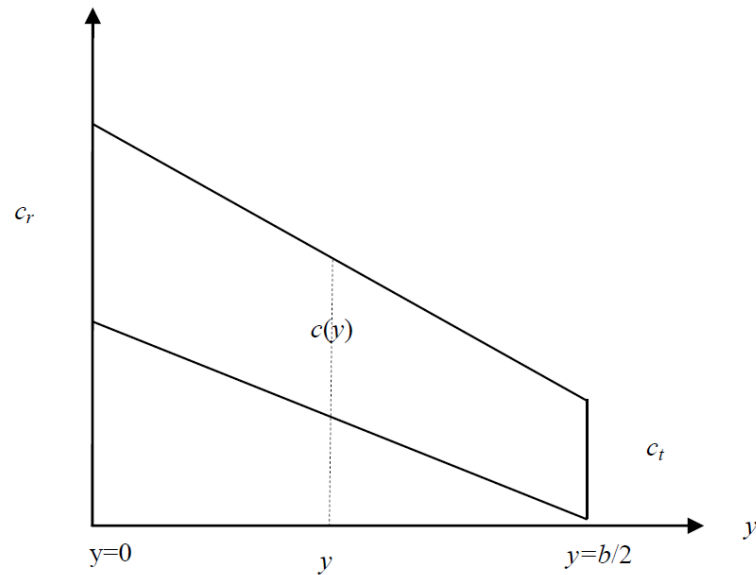
Rolling moment wake vortex effect \rightarrow R lift per unit span \rightarrow $dL(y)$ moment arm \rightarrow y

$$R = -\frac{1}{2} C_{L_\alpha} \rho U \int_{-b/2}^{b/2} y c(y) w(y) dy \quad (2)$$

Wing planform of following aircraft

Downwash of leading aircraft

Wing Geometry: Sweptback (of following aircraft)



root chord: c_r

tip chord: c_t

average chord: $2\bar{c} = c_t + c_r$

taper ratio: $\lambda \equiv \frac{c_t}{c_r}$

Chord as a function of span

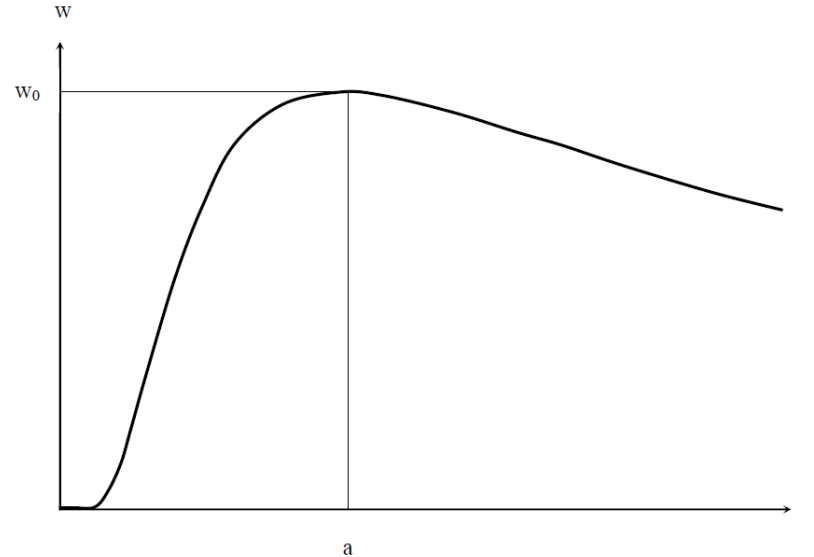
$$c(y) = c_r + (c_t - c_r) \frac{2|y|}{b}$$

alternatively:

$$c(y) = \frac{2\bar{c}}{1+\lambda} \left(1 + \frac{\lambda-1}{b} 2|y| \right) \quad (2)$$

Counter-rotating wing tip vortices (from leading aircraft) 1/2

One Hallock-Burnham (HB) vortex



tangential velocity $w(r)$ **Reference calculation**

$$w(r) = \frac{\Gamma_0}{2\pi} \frac{r}{r^2 + a^2}$$

radius **Vortex core radius**

Counter-rotating wing tip vortices (from leading aircraft) 2-2

Peak

$$w_0(r) = w(a) = \frac{\Gamma_0}{4\pi a} = \frac{\Omega a}{4}$$

$$w_0(r) = \frac{\Omega}{2} \frac{a^2 r}{r^2 + a^2}$$

Small r:

$$w_0(r) \sim \frac{\Omega r}{2}$$

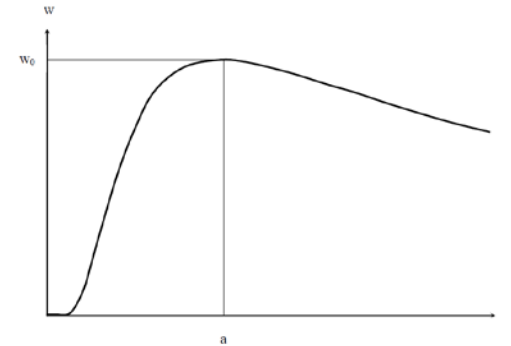
Large r:

$$w_0(r) \sim \frac{\Gamma_0}{4\pi r}$$

Rigid body

Potential vortex

Reference vorticity



Two counter-rotating HB Vortices

+ RIGHT

- LEFT

$$2w(y) = \Omega_r a_r^2 \frac{y - y_r}{a_r^2 + (y - y_r)^2} - \Omega_\ell a_\ell^2 \frac{y - y_\ell}{a_\ell^2 + (y - y_\ell)^2} \quad (3)$$

Vorticity: $\Omega_r, -\Omega_\ell$

Radius: a_r, a_ℓ

Position: y_r, y_ℓ

Rolling Moment Dependence on Encounter Conditions

Substitution (2) and (3) in (1) rolling moment

$$2R = -\frac{C_{L_\alpha} \rho U \bar{c} \Omega_r a_r^2}{1 + \lambda} \int_{-b/2}^{b/2} y \left(1 + \frac{\lambda - 1}{b} 2|y| \right) \frac{y - y_r}{a_r^2 + (y - y_r)^2} dy + \text{same for } (-\Omega_\ell, a_\ell, y_\ell)$$

After evaluation of integrals

$$R = -\frac{2}{1 + \lambda} C_{L_\alpha} \rho U_2 S_2 a^2 h \Omega(t)$$

lift slope → C_{L_α}
 mass density → ρ
 vortex core radius → U_2
 Taper ratio → λ
 airspeed → U_2
 wing area → S_2
 Vorticity function → $\Omega(t)$
 - varies with time (or distance from leading aircraft)

of following aircraft (index "2")

Encounter Parameters: h_r, h_ℓ, h

$$\Omega_r a_r^2 h_r - \Omega_\ell a_\ell^2 h_\ell = (\Omega_r - \Omega_\ell) a^2 h$$

right → $\Omega_r a_r^2 h_r$
 left → $\Omega_\ell a_\ell^2 h_\ell$
 total → $(\Omega_r - \Omega_\ell) a^2 h$
 vortex

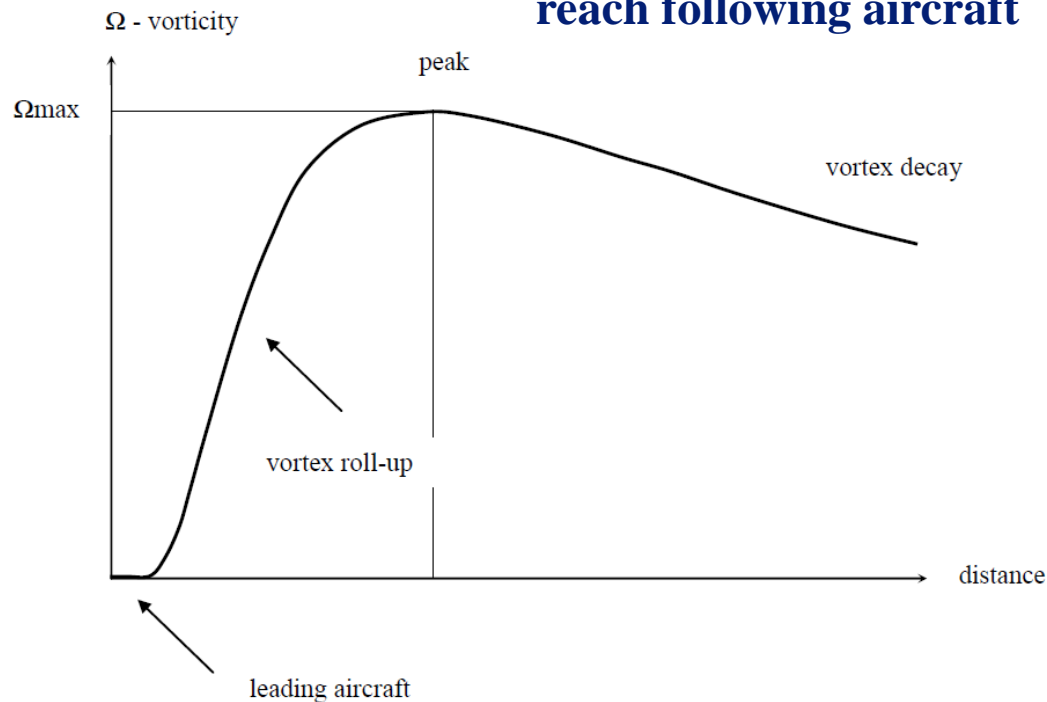
Vorticity as a Function of Distance (from leading aircraft)

1 – Leading aircraft trails two wing tip vortices.

2 – Wing tip vortices curl-up: vorticity increases.

3 – Weak atmospheric dissipation limits vorticity growth: reaches peak.

4 – Vorticity decays at larger distance behind leading aircraft \equiv longer time to reach following aircraft



Vorticity as a Function of Time (at following aircraft)

– Wake Vortex Strength of Leading Aircraft

$$\Gamma_0 = \frac{c_{\eta} W_1}{\rho U_1 S_1}$$

root chord (points to c_{η})
 weight (points to W_1)
 mass density (points to ρ)
 airspeed (points to U_1)
 wing area (points to S_1)

} **Leading Aircraft that creates the Wake**

– Vorticity at Following Aircraft

$$\Omega(t) = \frac{\Gamma_0}{2\pi\eta t} \exp\left(-\frac{a^2}{2\eta t}\right)$$

wake vortex strength of leading aircraft (points to Γ_0)
 Atmospheric diffusivity – vortex decay (points to $2\pi\eta t$)

a - vortex core radius

t - time

– Peak Vorticity

$$\Omega_{\max} = \Omega_{\max}(t_{\max}) = \frac{\Gamma_0}{\pi a^2 e}$$

→
occurs at time

$$t_* = \frac{a^2}{2\eta}$$

larger vortex radius (points to a^2)
 smaller dissipation (points to 2η)

WORST ENCOUNTER CONDITION

Roll Motion of the Following Aircraft

$$\begin{aligned}
 I_2 \ddot{\phi} &= m_2 (r_2)^2 \ddot{\phi} && \text{INERTIA TERM} \\
 &= -\frac{1}{2} \rho U_2 S_2 (b_2)^2 C_{\dot{\phi}} \dot{\phi} && \text{DAMPING TERM} \\
 &+ \rho S_2 b_2 (U_2)^2 C_{\delta} \delta(t) && \text{ROLL CONTROL TERM} \\
 &- \frac{2h}{1+\lambda} \frac{C_{L_{\alpha}}}{2\pi} W_1 \frac{U_2}{U_1} \frac{S_2}{S_1} c_{r_1} \frac{a^2}{\eta t} \exp\left(-\frac{a^2}{2\eta t}\right) && \text{WAKE EFFECT}
 \end{aligned}$$

Moment of inertia → I_2
 mass → m_2
 Gyration radius → $(r_2)^2$
 Roll acceleration → $\ddot{\phi}$
 Roll rate → $\dot{\phi}$
 Roll damping coefficient → $C_{\dot{\phi}}$

Rolling moment on following aircraft induced by the wake of the leading aircraft

INERTIA = - DAMPING + CONTROLS + WAKE VORTEX

CASE I – Sufficient Control Power to Counter Wake Effects (safe case)

INDUCED ROLLING MOMENT = AILERON CONTROLS MOMENT

AILERON DEFLECTION (OF FOLLOWING AIRCRAFT) THAT COMPENSATES WAKE VORTEX (OF LEADING AIRCRAFT)

$$\delta(t) = \frac{1}{C_\delta} \frac{2h}{1+\lambda} \frac{C_{L_\infty}}{2\pi} \frac{W}{\rho S_1 U_1 U_2} \frac{c_{r_1}}{b_2} \frac{a^2}{\eta t} \exp\left(-\frac{a^2}{2\eta t}\right)$$

INCREASES WITH:

- smaller aileron C_δ
- larger mean encounter parameter h
- smaller taper ratio λ
- larger lift slope C_{L_∞}
- smaller air density ρ (weaker aerodynamic forces)
- larger wing loading of leading aircraft: W_1 / S_1
- smaller velocity of both aircraft U_1, U_2 (need larger wake vortex strength)
- larger root chord of leading aircraft c_{r_1} (larger wake vortex strength)
- smaller span of following aircraft b_2 : less aileron moment arm;
- larger vortex core radius squared: a^2
- smaller dissipation η : less vortex decay.

CASE II – Free Aileron Response

$$\overset{\text{inertia}}{\ddot{\phi}_f} + \overset{\text{damping}}{\bar{\mu}\dot{\phi}_f} = 0$$

NO CONTROLS
NO WAKE

$$\overset{\text{Bank angle at time } t}{\phi_f(t)} = \phi_0 + \overset{\text{Initial roll rate}}{\frac{\dot{\phi}_0}{\bar{\mu}}} (1 - e^{-\bar{\mu}t})$$

Note: The term ϕ_0 is also labeled as 'Initial bank rate' in the original image.

DIMENSIONLESS DAMPING COEFFICIENT

$$\bar{\mu} \equiv \frac{1}{2} \frac{\rho U_2 S_2}{W_2 / g} \left(\frac{b_2}{r_2} \right)^2 C_{\dot{\phi}}$$

INCREASES WITH:

- larger air density ρ : lower altitude and larger aerodynamic forces;
- smaller wing loading W_2 / S_2 : light aircraft more easily damped;
- larger airspeed U_2 : larger forces.
- larger ratio of span b_2 to gyration radius r_2 squared: $(b_2 / r_2)^2$
- larger damping coefficient $C_{\dot{\phi}}$

CASE III – Forced Response to Aileron Deflection

$$\ddot{\phi}_c + \bar{\mu}\dot{\phi}_c = \nu$$

NO WAKE VORTEX

AILERON FORCING:

$$\nu = \frac{\rho}{g} \frac{S_2}{W_2} b_2 \left(\frac{U_2}{r_2} \right)^2 C_\delta \delta_{\max}$$

INCREASES WITH:

- larger air density: ρ
- lower wing loading S_2 / W_2
- larger span b , more effective ailerons;
- larger ratio of airspeed to gyration radius squared: larger ratio of aerodynamic forces to inertia forces;
- larger aileron coefficient C_δ
- larger aileron deflection δ_{\max}

Sum of Three Roll Responses

Total Bank Angle Response:

$$\phi(t) = \phi_f(t) + \phi_c(t) + \phi_w(t)$$

free controls wake

CONTROL RESPONSE

$$\phi_c(t) = 2 \frac{U_2}{b_2} \frac{C_\delta}{C_\dot{\phi}} \delta_{\max} t$$

BANK ANGLE INCREASES WITH:

- larger airspeed U_2 : larger aerodynamic forces.
- smaller span: less roll inertia;
- larger aileron coefficient: C_δ more roll control power;
- smaller roll damping coefficient: $C_\dot{\phi}$ less damping to oppose roll;
- larger aileron deflection δ_{\max}

Case IV: Wake Vortex Response

$$\ddot{\phi}_w + \bar{\mu} \dot{\phi}_w = -\frac{\bar{\xi}}{t} \exp\left(-\frac{a^2}{2\eta t}\right)$$

VORTEX EFFECT

$$\bar{\xi} \equiv \frac{2h}{1+\lambda} \frac{C_{L_\infty}}{2\pi} \frac{W_1/S_1}{W_2/S_2} \frac{U_2}{U_1} \left(\frac{a}{r_2}\right)^2 \frac{c_{r1} g}{\eta}$$

INCREASES WITH:

- larger encounter parameter h ;
- smaller taper ratio: rectangular more susceptible to vortex than swept/delta wing
- larger lift slope: more lift and roll
- larger ratio of wing loading of a/c 1 to wing loading to a/c 2: light a/c behind heavy a/c is worst case
- larger ratio of airspeed of a/c 2 to a/c 1 because a/c 2 catches wake of a/c 1 sooner;
- larger ratio of vortex core radius a to gyration radius r_2 squared;
- larger root chord of a/c 1
- less vortex decay: η

Case IV: Wake Vortex Response in terms of Exponential Integrals

DIMENSION LESS TIME: TIME t DIVIDED BY TIME t_{\max} OF PEAK VORTICITY

$$\tau \equiv \frac{t}{t_{\max}} = \frac{2\eta t}{a^2}$$

INCREASES FOR:

- stronger vortex decay: η
- smaller vortex core radius: a

ROLL RATE: $\Phi(\tau) \equiv \phi_w(t)$

$$\dot{\Phi}(\tau) = -\xi e^{-\mu\tau} \left[E_0(1/\tau) + \sum_{n=1}^{\infty} \frac{\mu^n}{n!} E_n(1/\tau) \right]$$

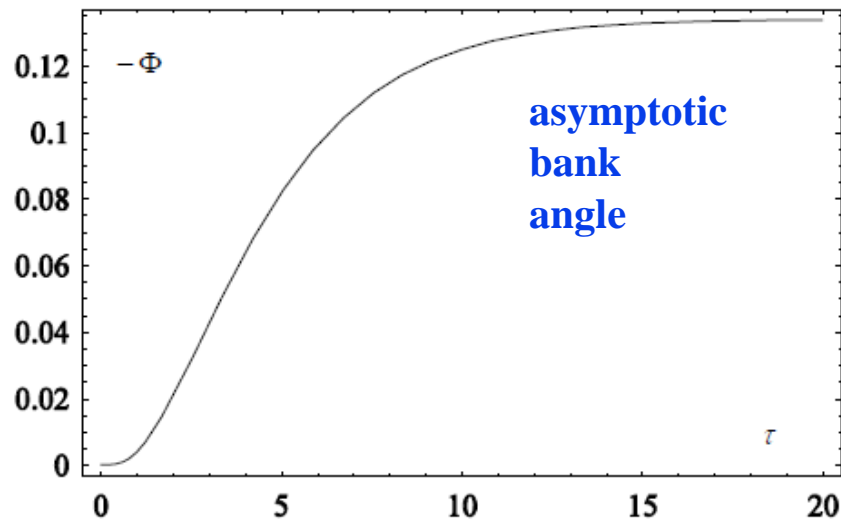
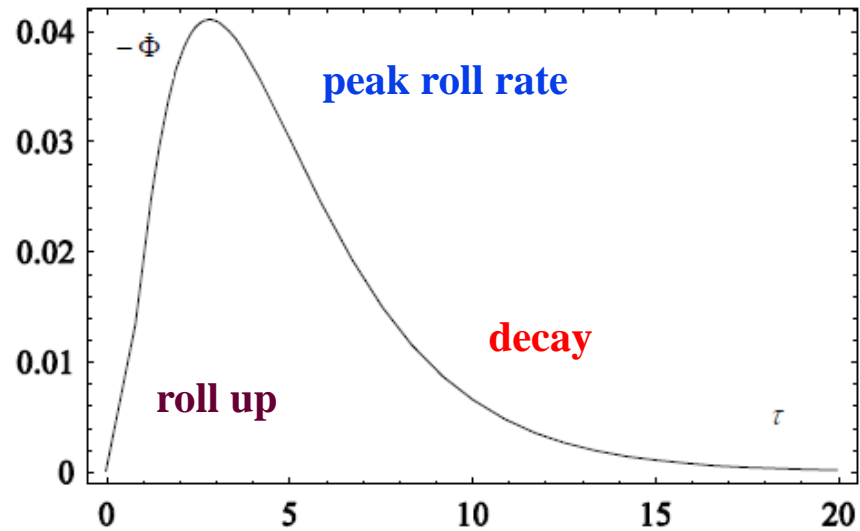
WHERE:

- vortex factor: $\xi \equiv \bar{\xi} \frac{a^2}{2\eta}$ - damping: $\mu \equiv \bar{\mu} \frac{a^2}{2\eta}$

- generalized exponential integral: $E_n\left(\frac{1}{\tau}\right) \equiv \int_0^{1/\tau} e^{-1/\tau} \tau^{n-1} d\tau$

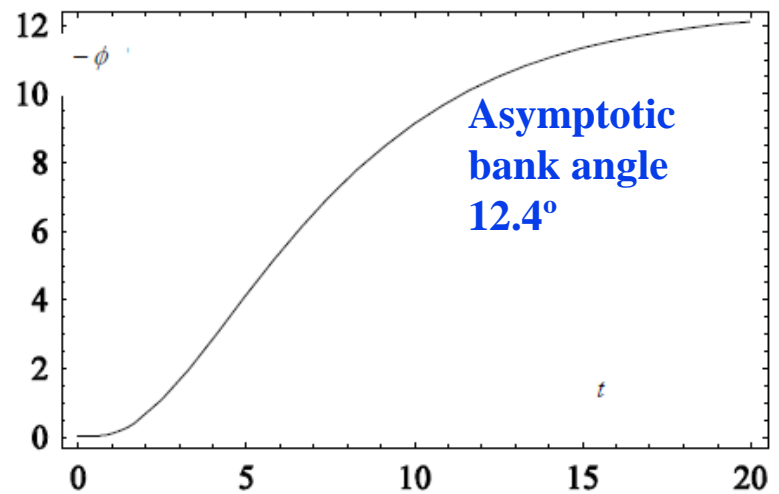
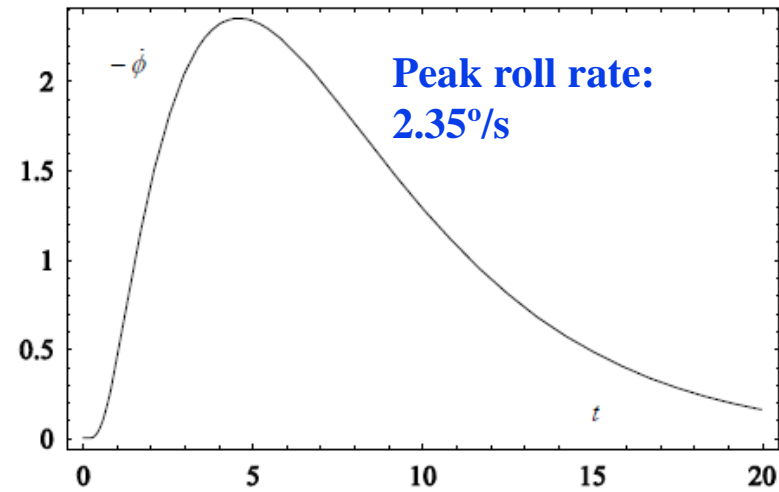
Roll Rate and Bank Angle

Dimensionless form valid for all aircraft pairs

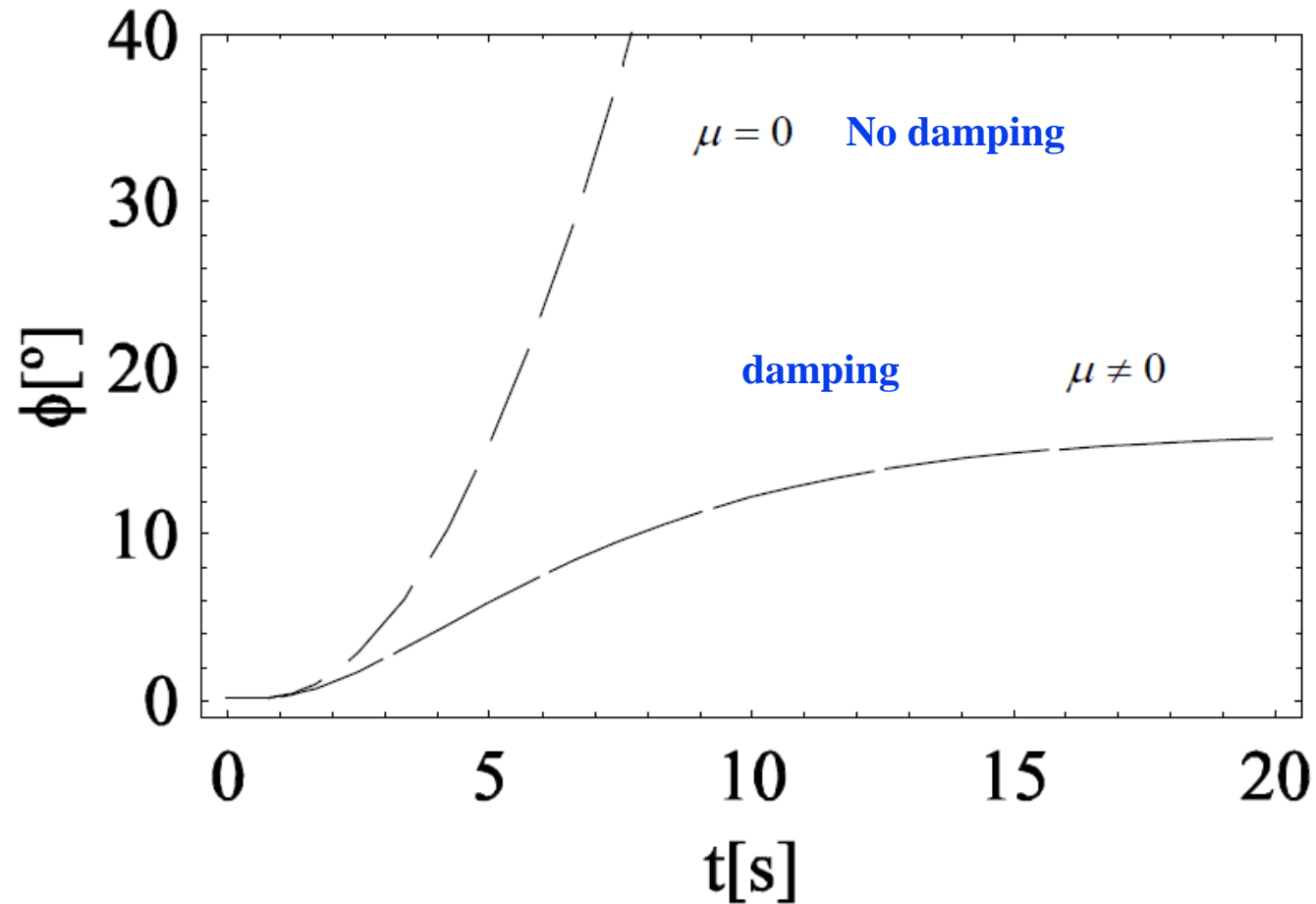


Special (B757-200) Aircraft Leading and Following: s-s

Worst
case-dimensional

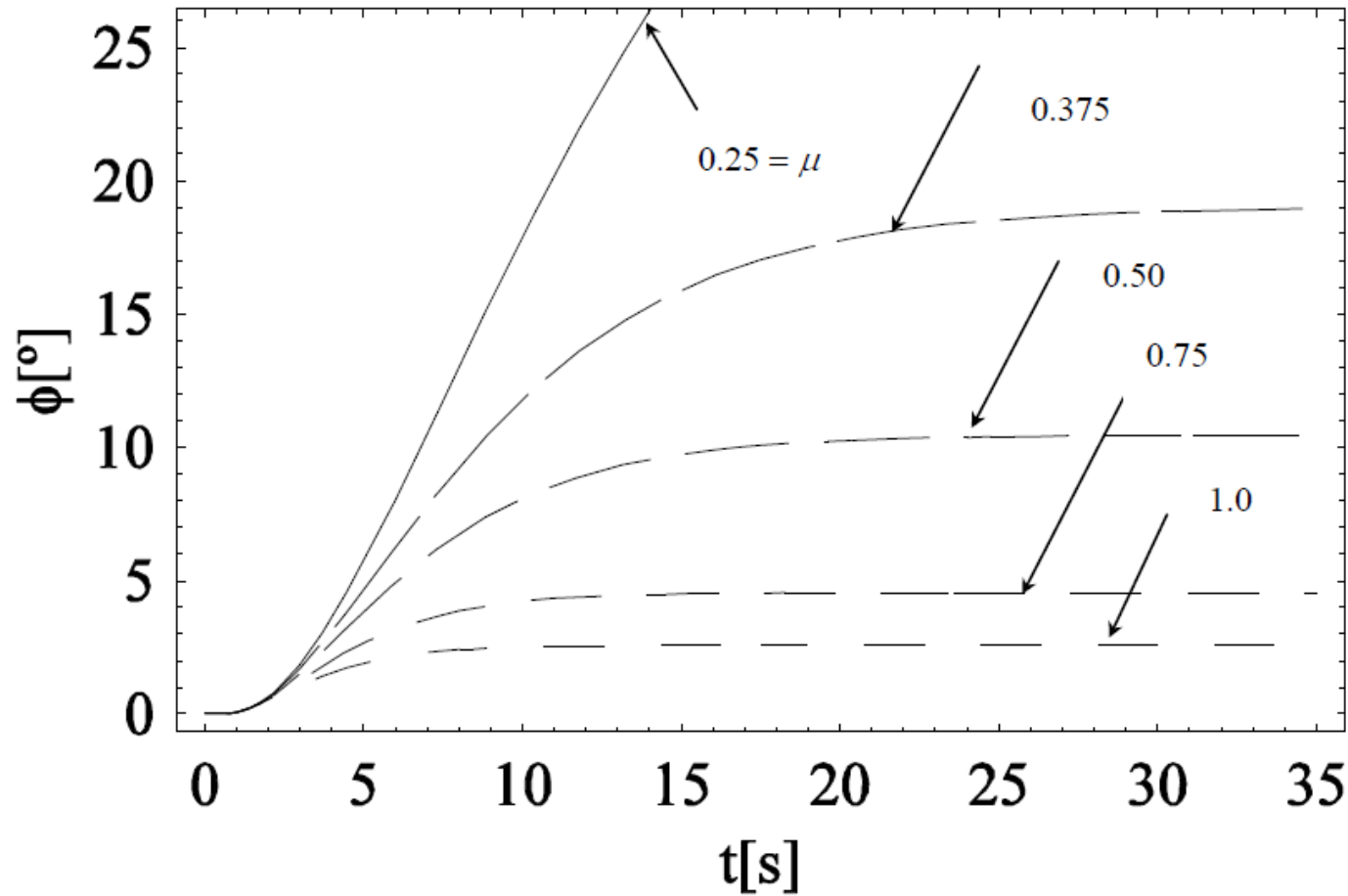


Without and with Roll Damping



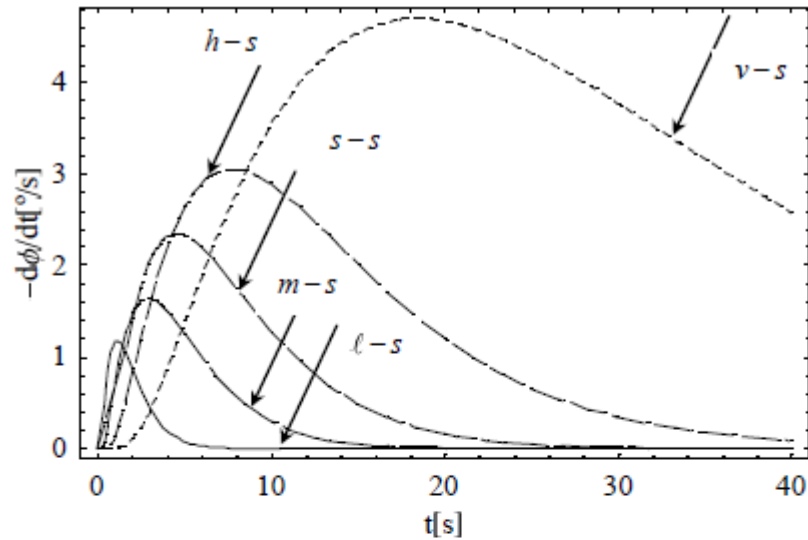
Weak and Strong Roll Damping

Weak and strong roll damping



**MORE
DAMPING
SMALLER
BANK
ANGLE**

Special (s) following aircraft



Leading Aircraft

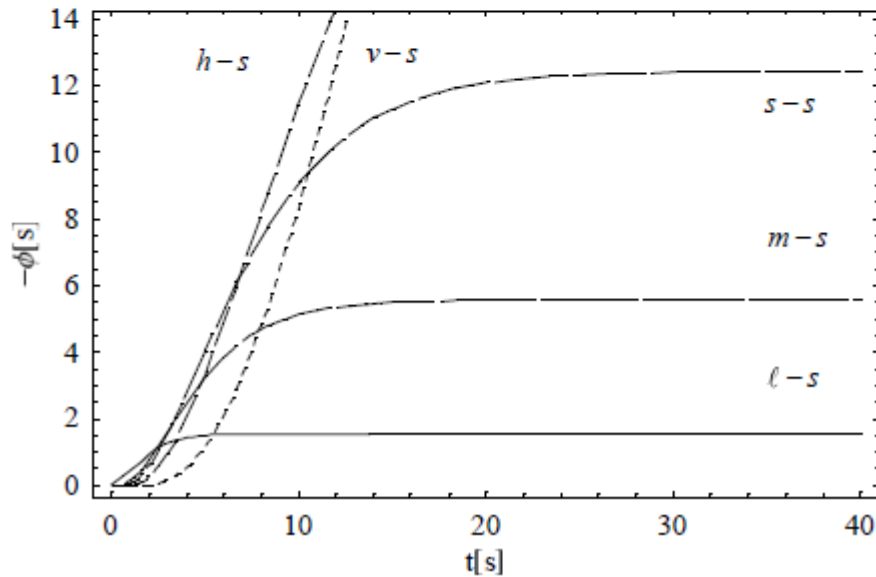
l – light: Jetstar

m – medium: B737 – 200

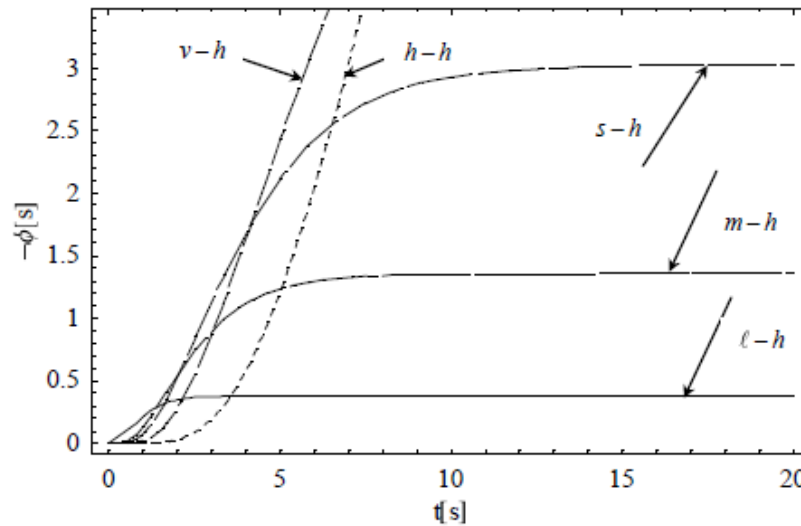
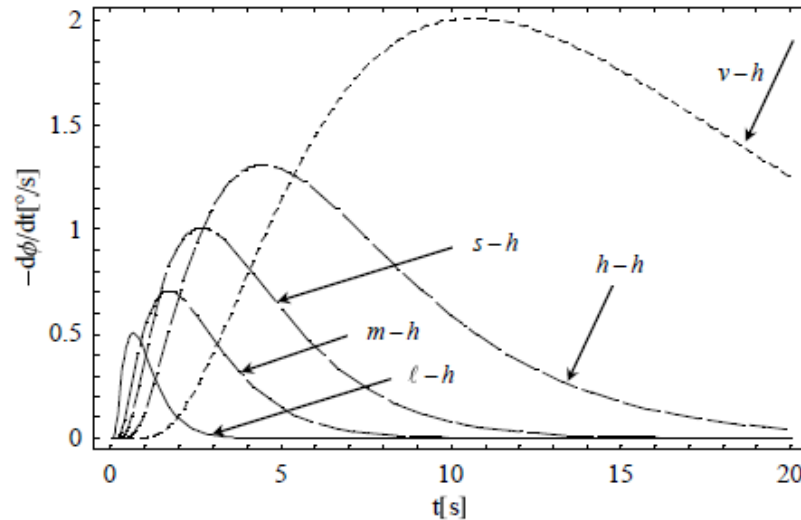
s – special; B757 – 200

h – heavy: B747 – 100

v – very large: A380 – 100



Heavy (h) following aircraft



Leading Aircraft

l – light: Jetstar

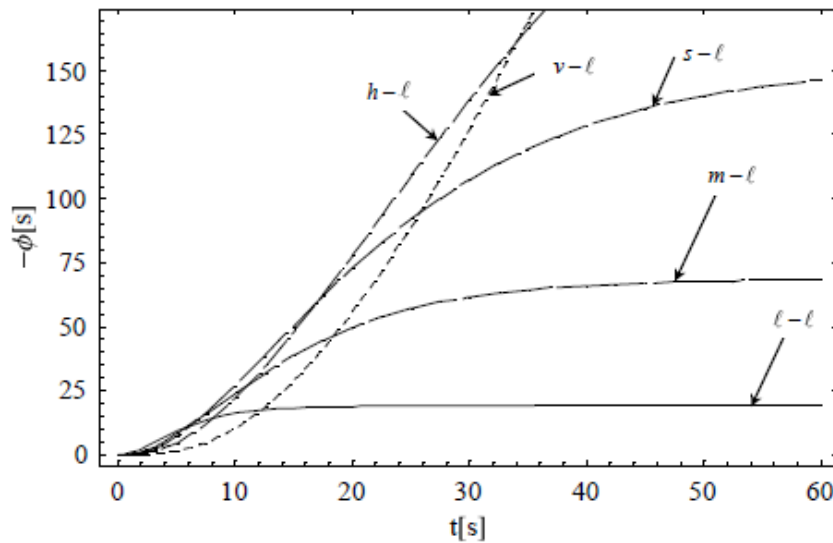
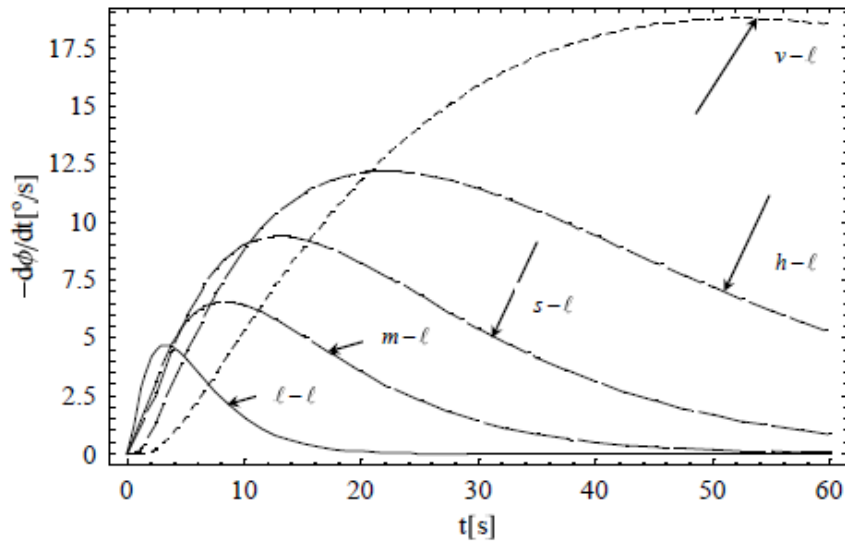
m – medium: B737 – 200

s – special; B757 – 200

h – heavy: B747 – 100

v – very large: A380 – 100

Light (l) following aircraft



Leading Aircraft

l – light: Jetstar

m – medium: B737 – 200

s – special; B757 – 200

h – heavy: B747 – 100

v – very large: A380 – 100

Table I – Wake vortex Effects on Following Special Aircraft

Aircraft		Roll rate		Bank angle	
Following	Leading	Peak value (°/s)	Peak time (s)	Asymptotic (°)	Asymptotic time (s)
special (s)	light (l)	1.17488	1.14958	1.5529	6.04563
	medium (m)	1.64483	2.94292	5.56561	15.4776
	special (s)	2.34975	4.59831	12.4232	24.1825
	heavy (h)	3.05468	7.77115	27.2938	40.6259
	very-large (v)	4.69951	18.3932	99.3859	96.7350

Table II – Wake vortex Effects on Following Heavy Aircraft

Aircraft		Roll rate		Bank angle	
Following	Leading	Peak value (°/s)	Peak time (s)	Asymptotic (°)	Asymptotic time (s)
heavy (h)	light (l)	0.502971	0.664053	0.377521	7.3898
	medium (m)	0.635871	2.30185	1.35304	7.88942
	special (s)	1.00594	2.65621	3.02017	12.3267
	heavy (h)	1.30773	4.48960	6.63532	20.8324
	very-large (v)	2.01189	10.6248	24.1614	49.3079

Table III – Wake vortex Effects on Following Light Aircraft

Aircraft		Roll rate		Bank angle	
Following	Leading	Peak value (°/s)	Peak time (s)	Asymptotic (°)	Asymptotic time (s)
light (l)	light (l)	4.6899	3.2679	19.05561	19.7537
	medium (m)	6.56458	8.36583	68.2952	50.5695
	special (s)	9.37798	13.0716	152.445	79.0149
	heavy (h)	12.1914	22.091	334.921	133.535
	very-large (v)	18.756	52.2865	1219.56	316.059

CONCLUSIONS (1/2)

- The roll response due to the wake vortex effects can be calculated for any pair of aircraft;
- The response is the same for all pairs of aircraft using suitable dimensionless variables;
- Using the parameters for each aircraft specifies the dimensionless roll rate and bank angle as a function of time;
- Peak roll rate and the time of its occurrence can be calculated;

CONCLUSIONS (2/2)

- Maximum bank angle can be determined and depends on damping to stop the rolling motion;
- Initial conditions (initial bank angle and roll rate) can be combined with aileron deflection and wake vortex effects;
- Wake vortex effects can be calculated for any separation between leading and following aircraft;
- Parametric dependences on aircraft characteristics and flight conditions are identified;
- Atmospheric model is simplified and is main limitation.